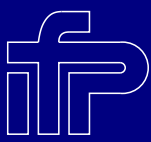


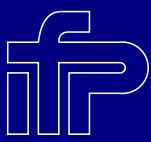
A Variable Péclet Upstream Weighting Scheme

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Contents

1. The variable Péclet upstream weighting scheme
2. Mathematical properties
3. Numerical results
4. Concluding remarks



Contents

1. The variable Péclet upstream weighting scheme
2. Mathematical properties
3. Numerical results
4. Concluding remarks

The Dead-Oil model

The coupled system

$$\begin{cases} \phi \frac{\partial s}{\partial t} + \text{div} \left(\Upsilon(\phi) \eta_o(s) \left(\rho_o \vec{g} - \vec{\nabla} (p + p_c(s)) \right) \right) = 0 \text{ on } \Omega \times (0, T) \\ -\phi \frac{\partial s}{\partial t} + \text{div} \left(\Upsilon(\phi) \eta_w(s) \left(\rho_w \vec{g} - \vec{\nabla} p \right) \right) = 0 \text{ on } \Omega \times (0, T) \end{cases}$$

Boundary conditions

$$\begin{cases} \Upsilon(\phi) \eta_w(s) \left(\rho_w \vec{g} - \vec{\nabla} p \right) \cdot \vec{n} = 0 \text{ on } \partial\Omega \times (0, T) \\ \Upsilon(\phi) \eta_o(s) \left(\rho_o \vec{g} - \vec{\nabla} (p + p_c(s)) \right) \cdot \vec{n} = 0 \text{ on } \partial\Omega \times (0, T) \end{cases}$$

Initial condition

$$s(x, 0) = s_{ini}(x)$$

The decoupled system

$$\begin{cases} \operatorname{div}(\vec{Q}) = 0, & \text{on } \Omega \times (0, T), \\ \phi \frac{\partial s}{\partial t} + \operatorname{div}\left(f(s, \vec{Q}, \vec{G}) - \Upsilon(\phi) \vec{\nabla} \varphi(s)\right) = 0, & \text{on } \Omega \times (0, T), \end{cases}$$

where

- $\vec{Q} = \Upsilon(\phi) \left(\left(\eta_o(s)\rho_o + \eta_w(s)\rho_w \right) \vec{g} - \eta_T(s) \vec{\nabla} \bar{p} \right),$
- $\bar{p} = p + \int_0^s \frac{\eta_o}{\eta_T}(v) p'_c(v) dv,$
- $f(s, \vec{Q}, \vec{G}) = \frac{\eta_o}{\eta_T}(s) \vec{Q} + \frac{\eta_o \eta_w}{\eta_T}(s) \vec{G},$
- $\vec{G} = \Upsilon(\phi) (\rho_o - \rho_w) \vec{g},$
- $\varphi'(s) = \frac{\eta_o(s) \eta_w(s)}{\eta_o(s) + \eta_w(s)} p'_c(s).$

The finite volume scheme (1)

Discretization of the total mass equation

$$\sum_{L \in N(K)} Q_{K,L}^{n+1} = 0$$

where

- $Q_{K,L}^{n+1} = \Upsilon_{K|L} \left(\left(\eta_{o,K|L}^n \rho_o + \eta_{w,K|L}^n \rho_w \right) g \delta z_{K,L} - \eta_{T,K|L}^n \delta \bar{p}_{K,L}^{n+1} \right),$
- for all $\alpha \in \{o, w, T\}$

$$\eta_{\alpha,K|L}^n = \frac{\left(d(x_L, K|L) + d(x_K, K|L) \right) \eta_{\alpha}(s_K^n) \eta_{\alpha}(s_L^n)}{\eta_{\alpha}(s_K^n) d(x_L, K|L) + \eta_{\alpha}(s_L^n) d(x_K, K|L)}.$$

The finite volume scheme (2)

Discretization of the oil mass equation (upwind scheme)

$$m(K)\phi_K \frac{s_K^{n+1} - s_K^n}{\delta t} + \sum_{L \in N(K)} F(s_K^n, s_L^n, Q_{K,L}^{n+1}, G_{K,L}) - \Upsilon_{K|L}(\varphi(s_L^n) - \varphi(s_K^n)) = 0$$

where

- $G_{K,L} = \Upsilon_{K|L}(\rho_o - \rho_w)g\delta z_{K,L}$,
- $F(s_K^n, s_L^n, Q_{K,L}^{n+1}, G_{K,L}) = \frac{(\eta_o)_{K|L}^{n+1} \left(Q_{K,L}^{n+1} + (\eta_w)_{K|L}^{n+1} G_{K,L} \right)}{(\eta_o)_{K|L}^{n+1} + (\eta_w)_{K|L}^{n+1}}$,
- the upwind saturations in the terms $(\eta_\alpha)_{K|L}^{n+1}$, $\alpha \in \{o, w\}$ are determined by the values of $Q_{K|L}^{n+1}$ and $G_{K,L}$.

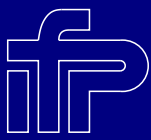
The finite volume scheme (3)

Discretization of the oil mass equation (variable Péclet scheme)

$$m(K)\phi_K \frac{s_K^{n+1} - s_K^n}{\delta t} + \sum_{L \in N(K)} \mathcal{F}(\theta_{K|L}^{n+1}, s_K^n, s_L^n, Q_{K,L}^{n+1}, G_{K,L}) - \Upsilon_{K|L}(\varphi(s_L^n) - \varphi(s_K^n)) = 0$$

where

- $\mathcal{F}(\theta, a, b, Q, G) = \theta F(a, b, Q, G) + (1 - \theta)F\left(\frac{a+b}{2}, \frac{a+b}{2}, Q, G\right),$
- $$\theta_{K|L}^{n+1} = \max\left(0, 1 - \frac{\Upsilon_{K|L}(\varphi(s_L^n) - \varphi(s_K^n))}{\Lambda_{K,L}^{n+1}(s_K^n, s_L^n)}\right), \quad (1)$$
- $$\Lambda_{K,L}^{n+1}(a, b) = F\left(\frac{a+b}{2}, \frac{a+b}{2}, Q_{K,L}^{n+1}, G_{K,L}\right) - F(a, b, Q_{K,L}^{n+1}, G_{K,L}).$$



Contents

1. The variable Péclet upstream weighting scheme
2. Mathematical properties
3. Numerical results
4. Concluding remarks

Stability and Existence

Stability of the saturation calculation

$$0 \leq s_K^n \leq 1$$

under (1) and the CFL condition

$$\delta t \leq \inf_{K \in \mathcal{T}} \left(\frac{\phi_K m(K)}{\sum_{L \in N(K)} \left(2C_\eta (|Q_{K,L}^{n+1}| + |G_{K,L}|) + \Upsilon_{K|L} L_\varphi \right)} \right). \quad (2)$$

Existence of solutions to the discrete system

An L^2 -pressure estimate and a topological degree argument give the existence of solutions to the discrete system in pressure and saturation.

Convergence

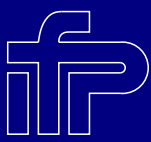
Under assumptions on \vec{Q} , δt , $\theta_{K|L}^{n+1}$ and the sequence of the discretizations $(\mathcal{M}_m)_{m \in \mathbb{N}}$ we have

1. $s_m \xrightarrow{L^2(\Omega \times (0, T))} s \in L^\infty(\Omega \times (0, T)),$

2. $\varphi(s) \in L^2((0, T), H^1(\Omega)),$

3.
$$\begin{aligned} &\forall \psi \in C_{test}, \\ &\int_0^T \int_\Omega s \psi_t + f(s, \vec{Q}, \vec{G}) \cdot \vec{\nabla} \psi - \vec{\nabla} \varphi(s) \cdot \vec{\nabla} \psi \, dx dt + \\ &\int_\Omega s_{ini} \psi(\cdot, 0) dx = 0 \end{aligned}$$

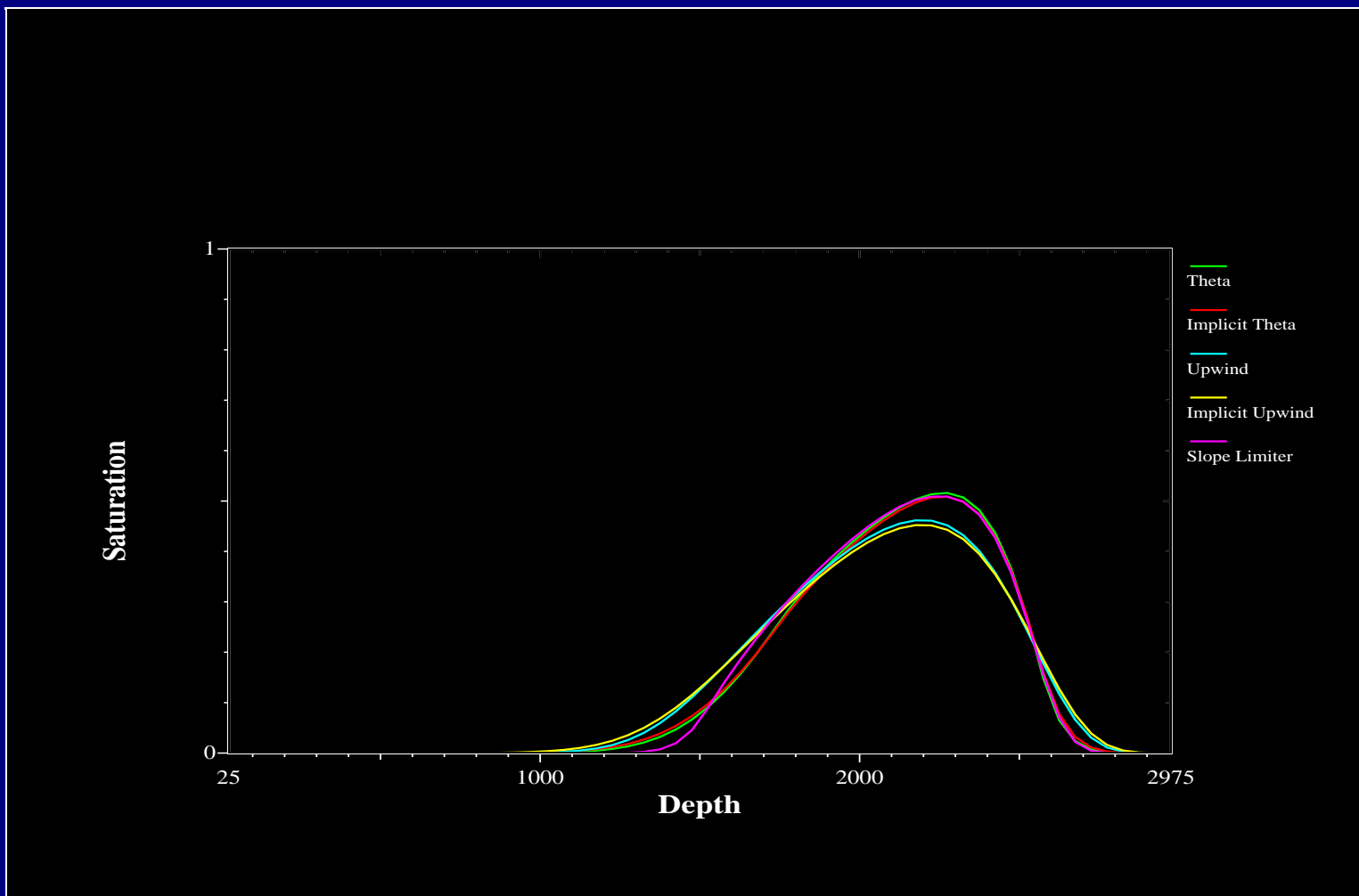
where $C_{test} = \{h \in H^1(\Omega \times (0, T)) / h(\cdot, T) = 0\}.$



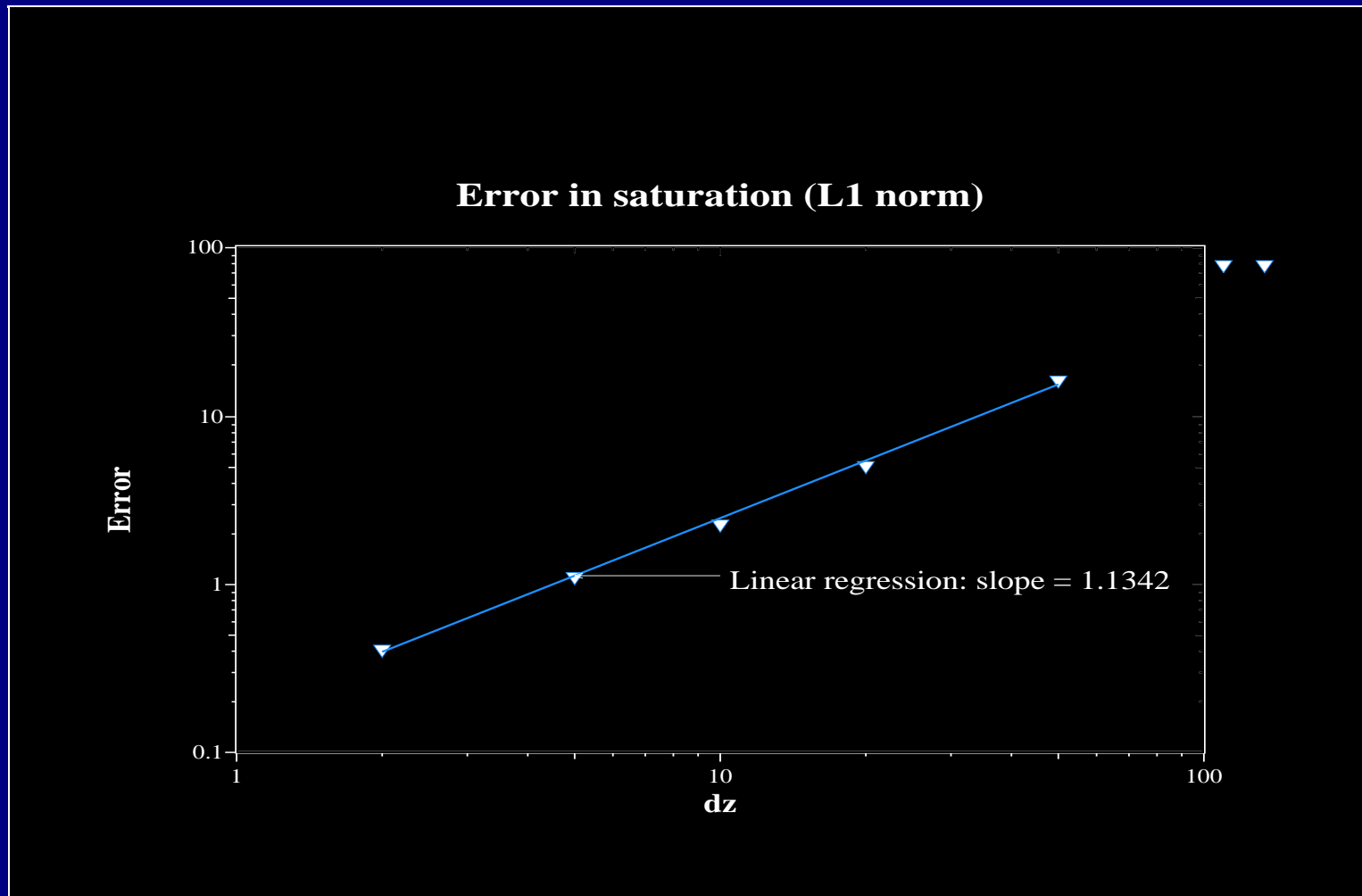
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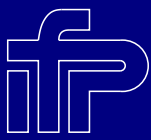
1. The variable Péclet upstream weighting scheme
2. Mathematical properties
3. Numerical results
4. Concluding remarks

1D-test



Numerical convergence : Error in saturation





Contents

1. The variable Péclet upstream weighting scheme
2. Mathematical properties
3. Numerical results
4. Concluding remarks

Properties of the scheme :

- cheap and accurate,
- use for multidimensional domains,
- the implicit form is simple to implement.